

Unmanned aircraft for detection and monitoring of invasive plant species

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Why plant invasions?

- threat to biodiversity, ecosystem functioning, traditional landscapes
- impact grows despite the worldwide efforts to control and eradicate
- once fully established - hard to permanently eliminate



fast and precise monitoring crucial

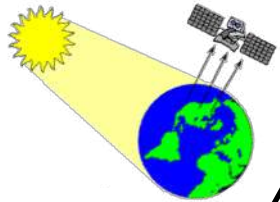


Why remote sensing?

- improving early detection of invading plants
- fast, repeatable and efficient computer-assisted methods of timely monitoring
- reducing the costs of field campaigns → more efficient and less expensive management and eradication
- information on spatial structure of invasions



Which data are available?



long time series

satellite

Landsat (30m), Sentinel
FREE (10m)

costly
VHR

- optimal timing of the campaign (phenology)
- targeted monitoring
- DSM as a by-product



flexible

UAV

RGB-NIR

aerial

MSS

color

PAN

(historical)

long time series

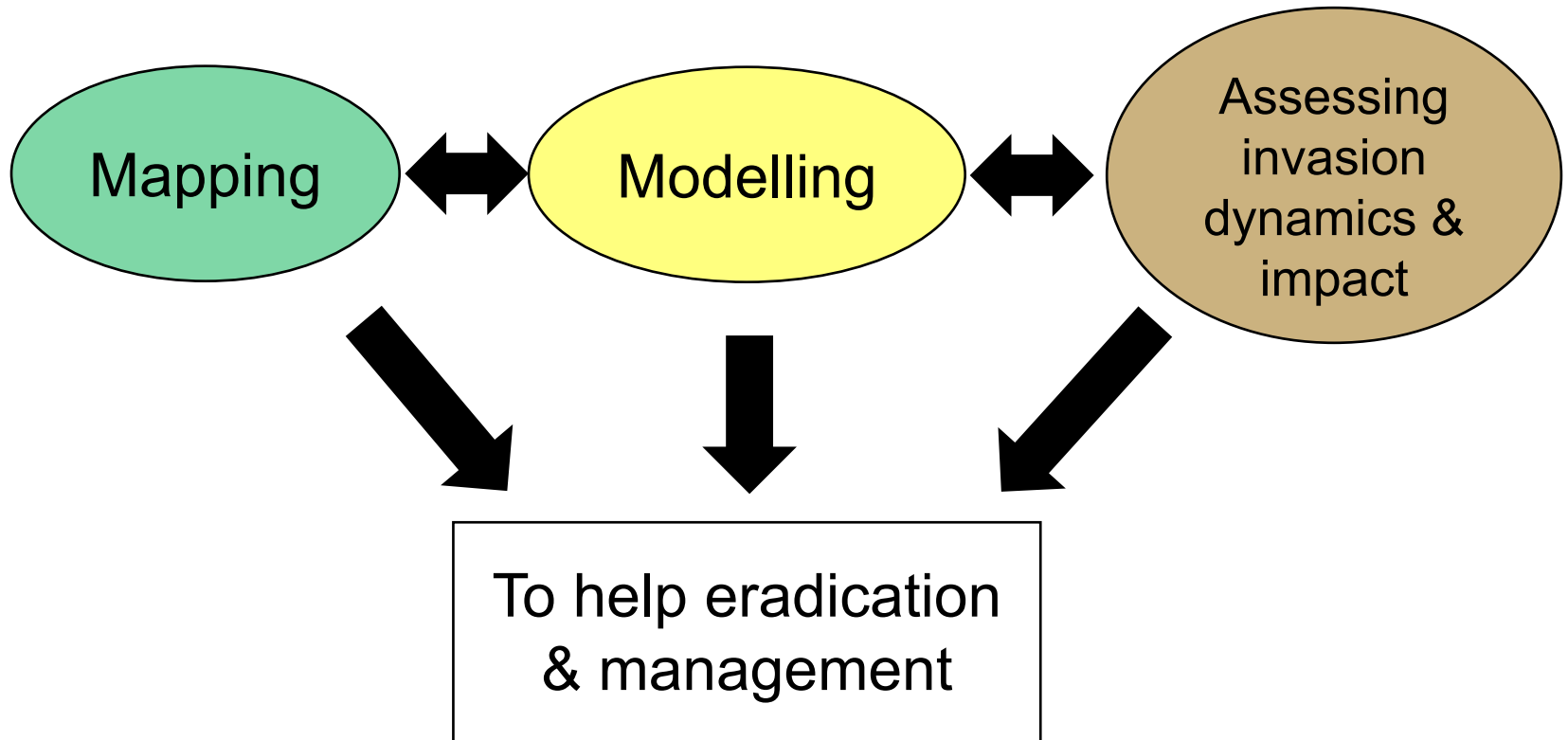


spectral

spatial resolution

- not standardized
- complex
- constrains

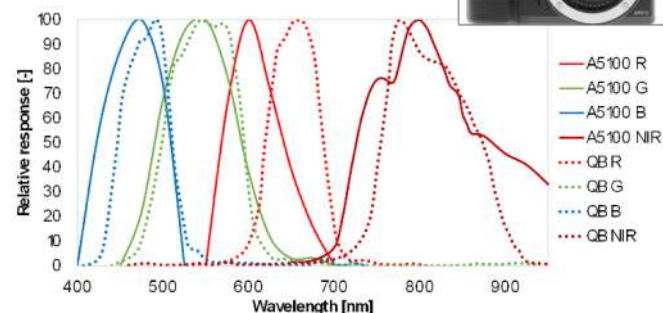
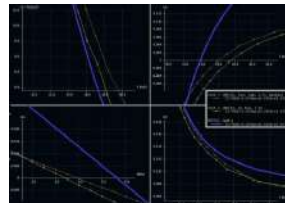
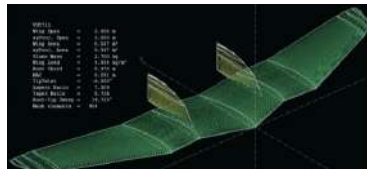
How can we use RS to tackle invasions?






What unmanned aircraft?

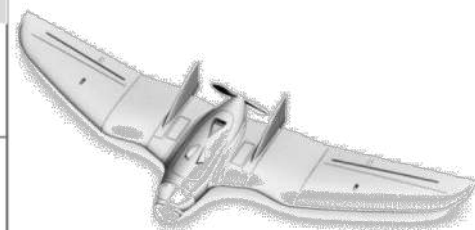


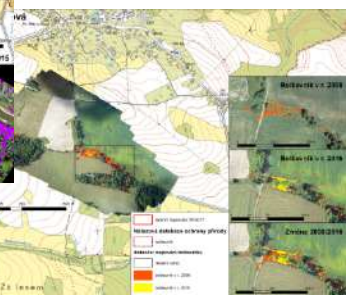
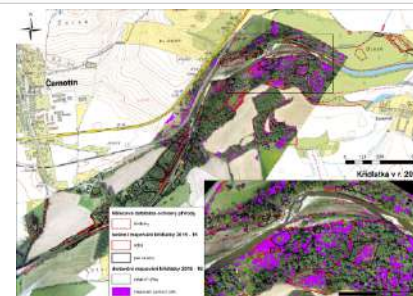
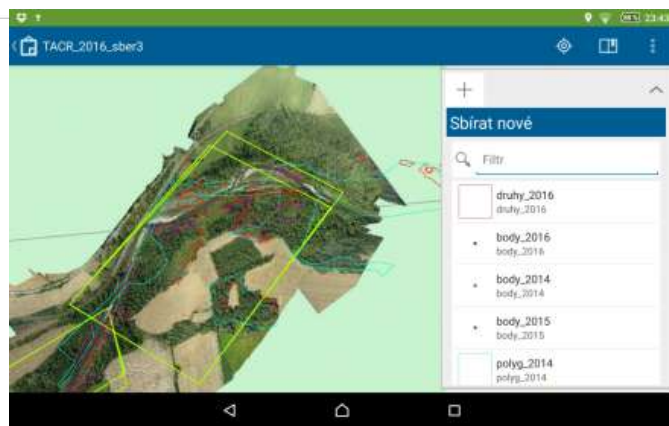
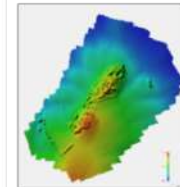
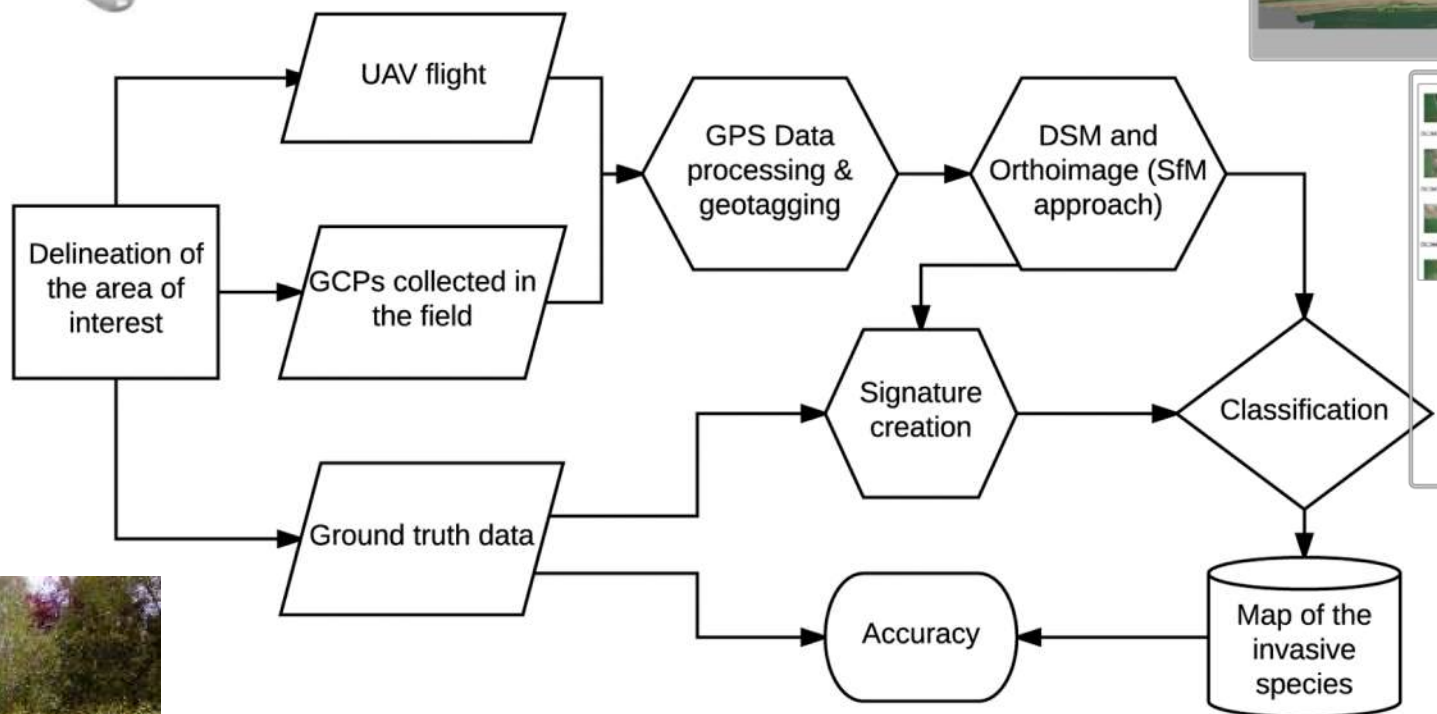
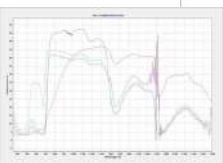
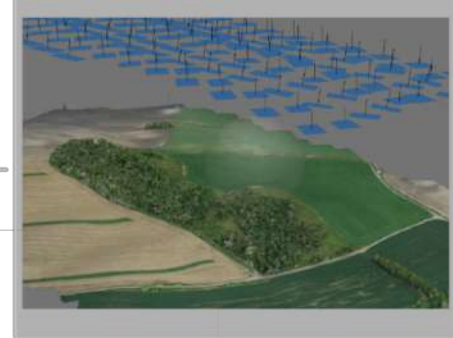
Our goal – inexpensive approach for nature conservation



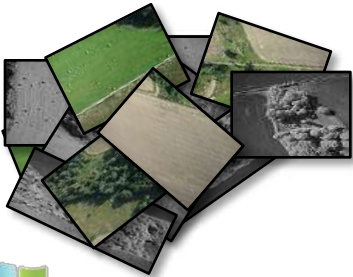
	VUT 720	VUT 712	VUT 713
			
Span	2.6 m	2.1 m	2.0m
Length	1.3 m	0.9 m	0.7m
mTOW	2.2 kg	3.1 kg	3kg
vc	15 m/s	17 m/s	18m/s
Endurance	1 hr	0.9 hr	0.8hr
Power	360 W	800 W	600 W
Payload	0.3 kg	0.8 kg	0.9 kg
Autopilot	APM2.5+ autopilot	Pixhawk autopilot	Pixhawk autopilot
Camera	1x Canon S100+ 1x GoPro	2x Canon S100 stabilized	2x Sony A5100 + E20/2.8
Based on	Multiplex Cularis	SkyWalker X8	RVJET

Camera setup	Stabilization	Georeferencing	Triggering	Comments
2x Canon S100 (VIS + NIR)	External mechanical	Internal GPS / Precise shutter time	Intervalometer ~0.5Hz (CHDK scripting)	Light solution, can be customized by CHDK, prone to dust
2x Sony A5100 (VIS+NIR)	No need	Autopilot DGPS – trigger log	Distance based – from autopilot system	Sensor size, fixed lens, stabilization not needed, better precision
Sony A6000 (VIS) Sony A5100 (NIR)	No need	Autopilot DGPS – trigger log	Distance based – from autopilot system	Sensor size, fixed lens, X-contact synchro, best orthomosaic

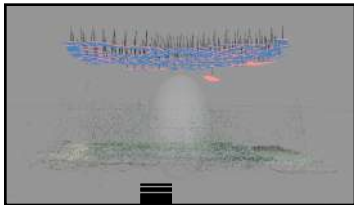


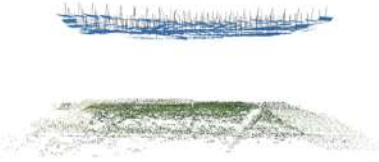
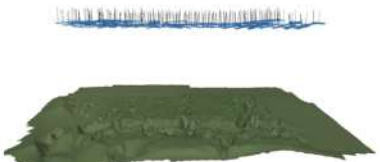
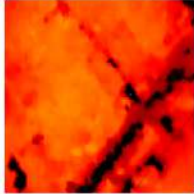

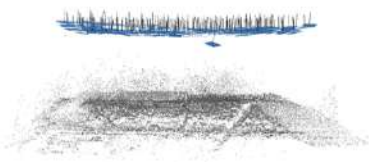
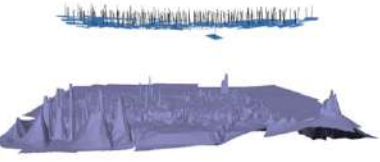
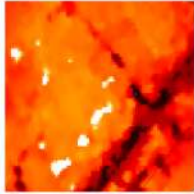

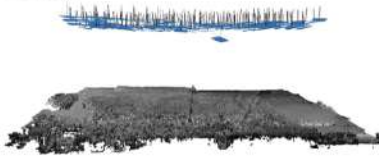
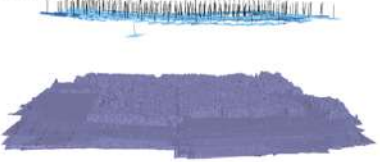



Pre-processing

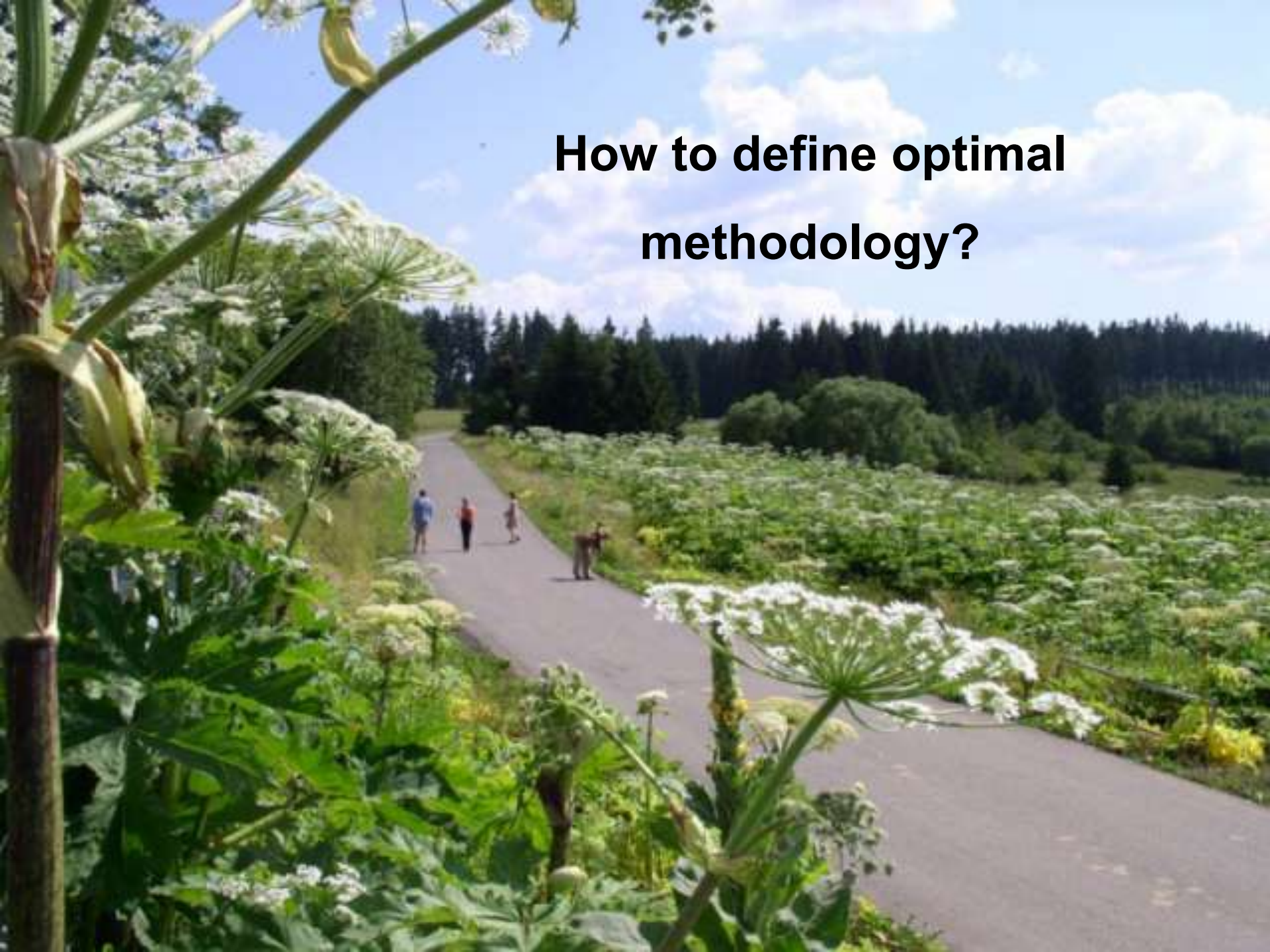


PhotoScan
3D Modeling and Mapping



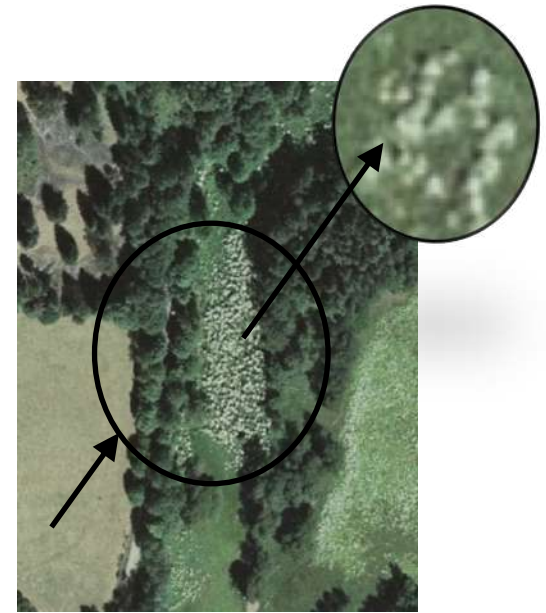
	Point cloud	3D model	DEM	Mosaic
Only VIS data	SPC clean and well defined 	clean and realistic 		
VIS+NIR data coprocessed	SPC "noisy" 	unrealistic artifacts 		
VIS+NIR data coprocessed + aggressive depth filtering for dense point cloud	DPC clean 	clean 		

**How to define optimal
methodology?**

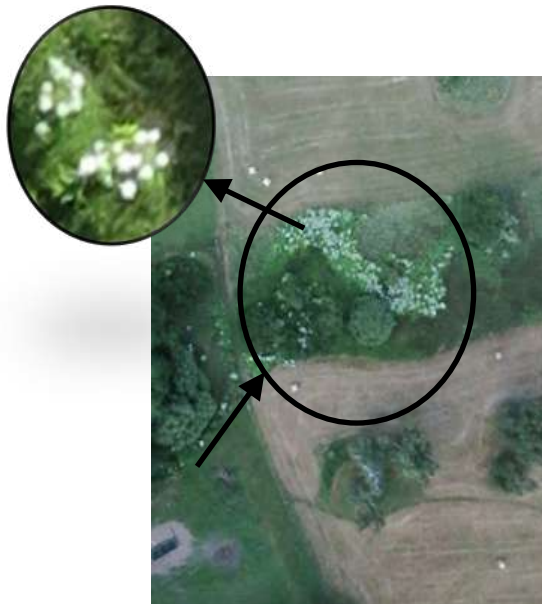


1. Role of spatial resolution

Giant hogweed



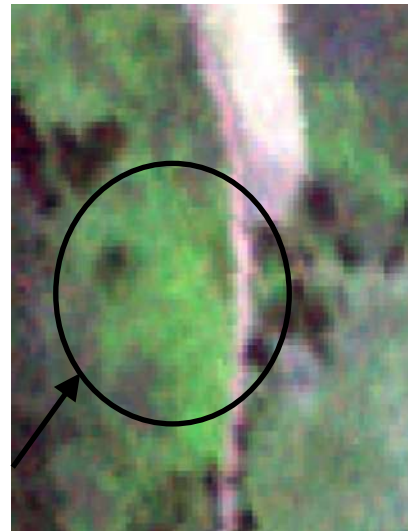
Aerial PAN (1962, 0.5m) Aerial color (2006, 0.5m)



UAV (2015, 5cm)

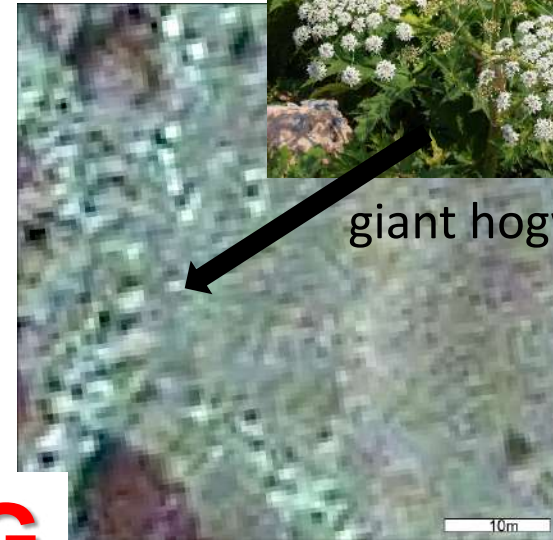


Pleiades (2013, 2.8m)



RapidEye (2010, 6.5m)

2. Role of temporal resolution



giant hogweed

RIGHT TIMING

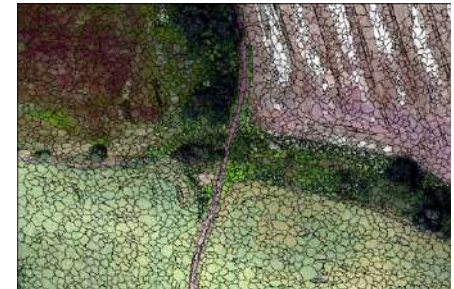
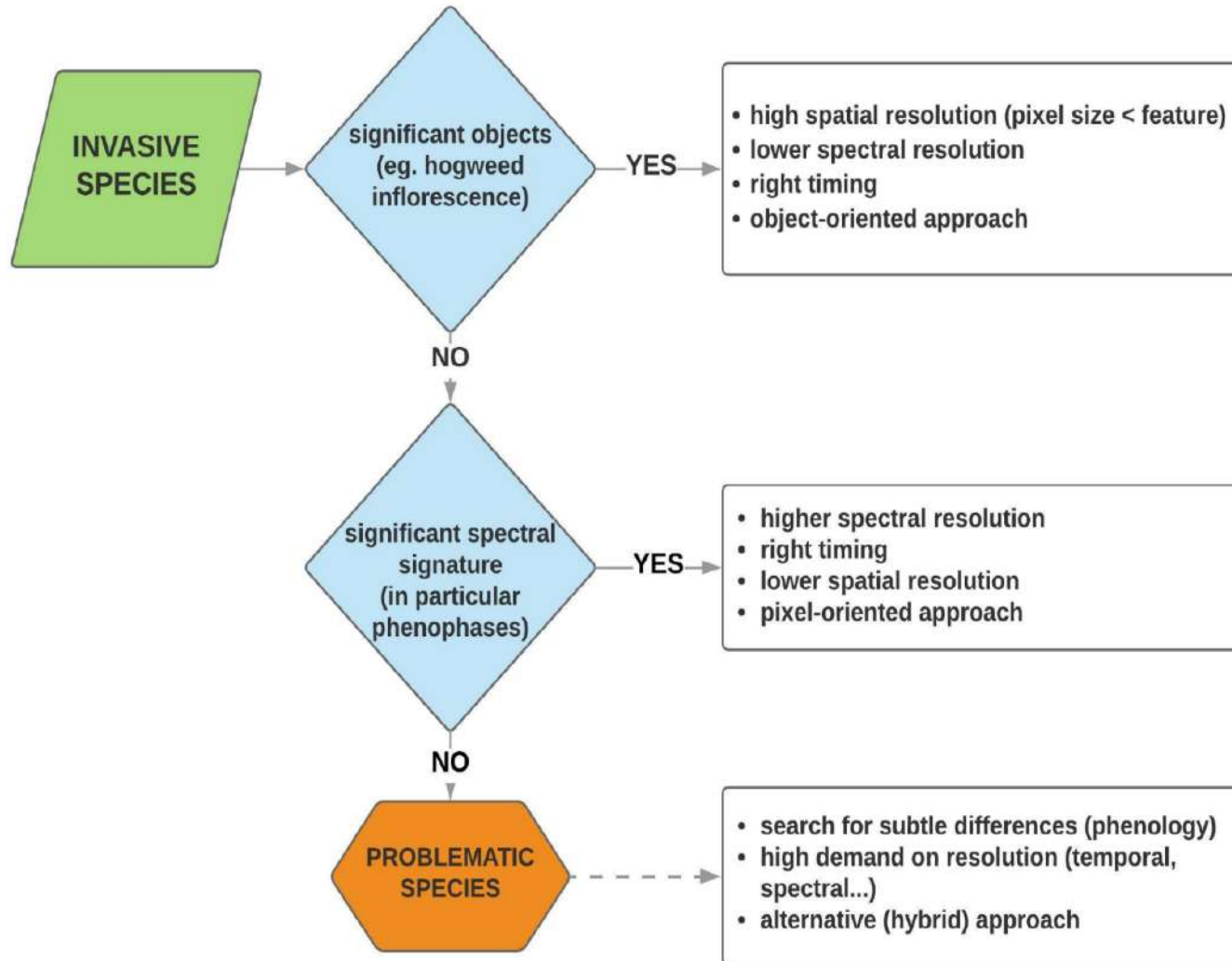


knotweeds

Ailanthus altissima



3. Choice of classification approach



Accuracy – giant hogweed

Data	Resolution	Phenology	Method	User's accuracy	Producer's accuracy
RapidEye	6.5 m	early flowering	pixel (MaxLike) / OBIA	65 / 44%	76 / 65%
Pleiades	2.8 m	middle flowering	pixel / OBIA (RF)	86 / 70%	94 / 99%
aerial PAN	0.5 m	middle flowering	OBIA	89.0%	80.5%
aerial color	0.5 m	middle flowering	OBIA	57.4%	94.3%
UAV RGB/NIR	0.05 m	middle flowering	OBIA	99.0%	99.8%
aerial PAN	0.5 m	final-size/ripe fruiting	OBIA	86.4%	68.9%
aerial MSS	0.5 m	ripe fruiting	OBIA	51.6%	74.2%
			pixel-based (MaxLike)	42.0%	28.5%



Phenology, method and resolution matters

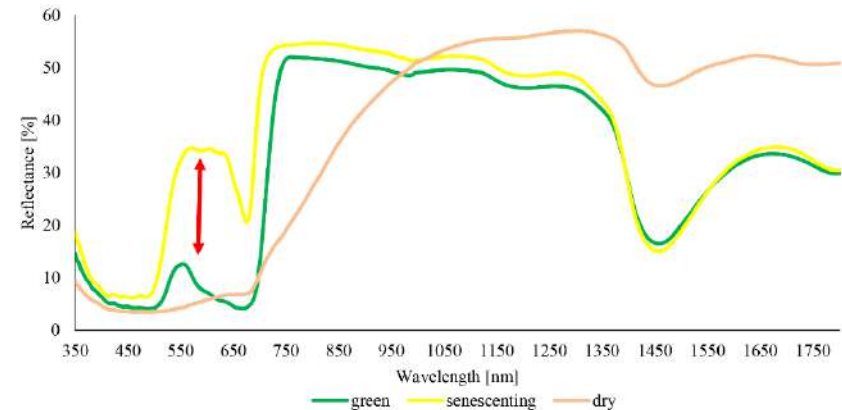
Accuracy – Asian knotweeds

Data	Resolution	Phenology	Method	User's accuracy	Producer's accuracy
Pleiades 1B	0.5 / 2m	green	pixel (RF)	44%	95%
UAV RGB/NIR	0.05m	green	pixel (SVM)	60%	92%
		senescence	pixel (MaxLike/SVM)	80 / 54%	78 / 95%
UAV RGB/NIR + BTBR / Canopy Height Model	0.05m	green	OBIA (RF)	80 / 78%	83 / 86%



$$BTBR_{mod} = \frac{(NIR_{off} / R_{on}) - (G_{off} / G_{on})}{(NIR_{off} / R_{on}) + (G_{off} / G_{on})}$$

Exotic knotweeds

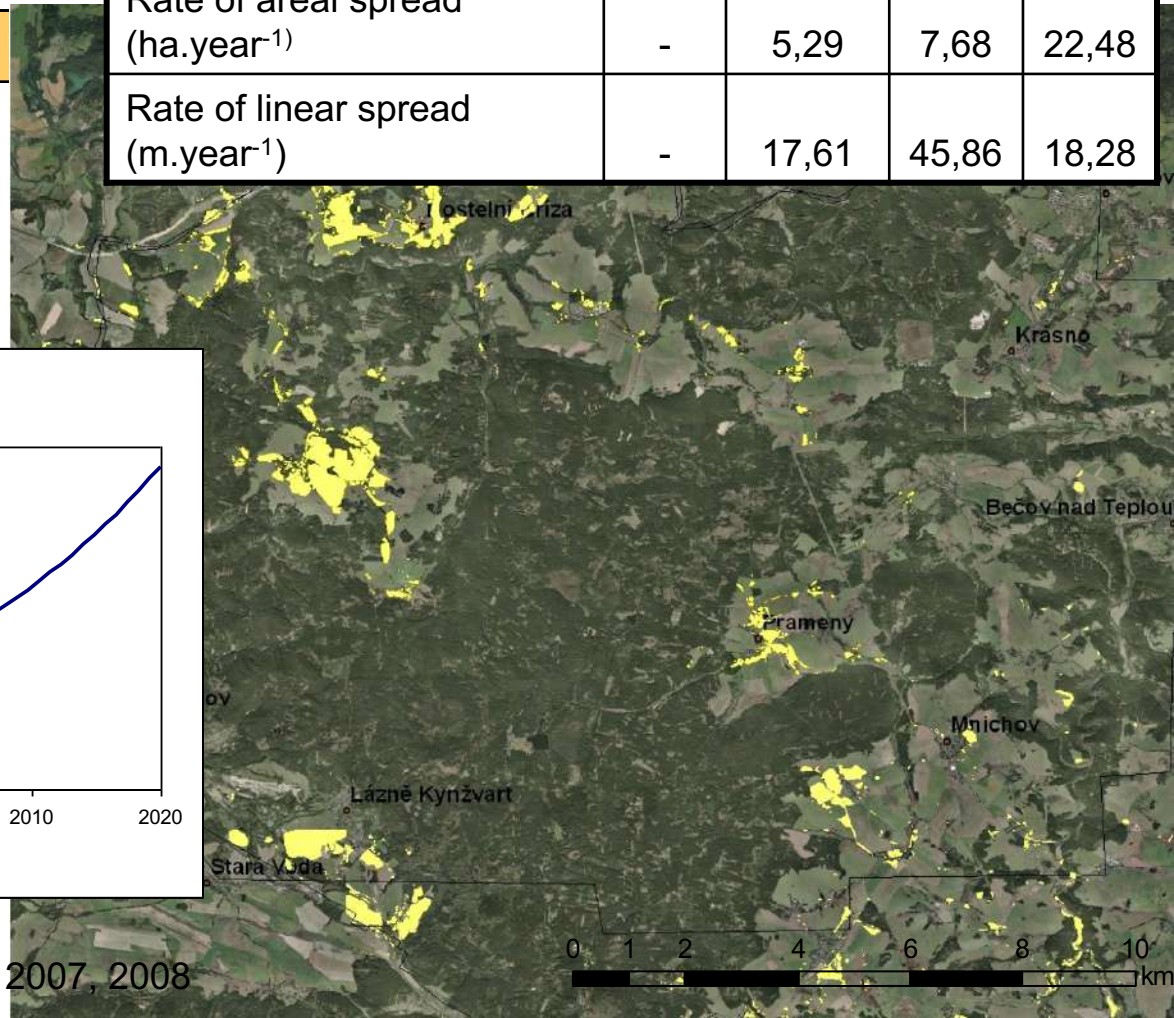


Müllerová et al. (2017) Frontiers in Plant Science; Martin et al. (2018)

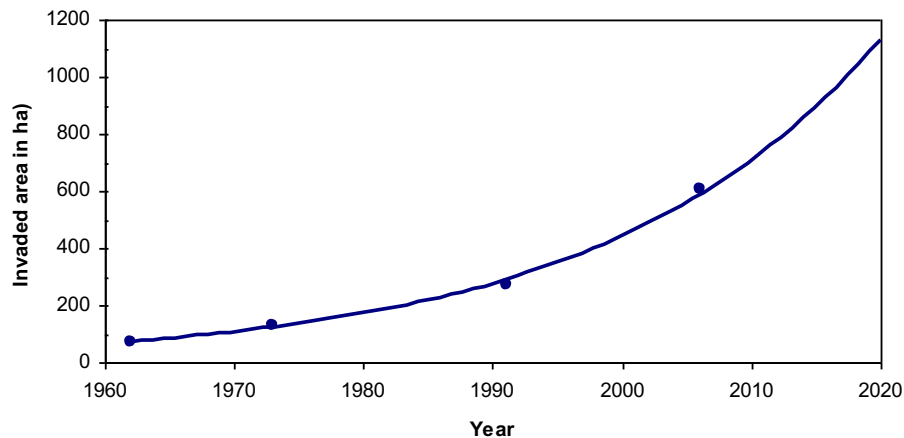
Invasion at the landscape scale

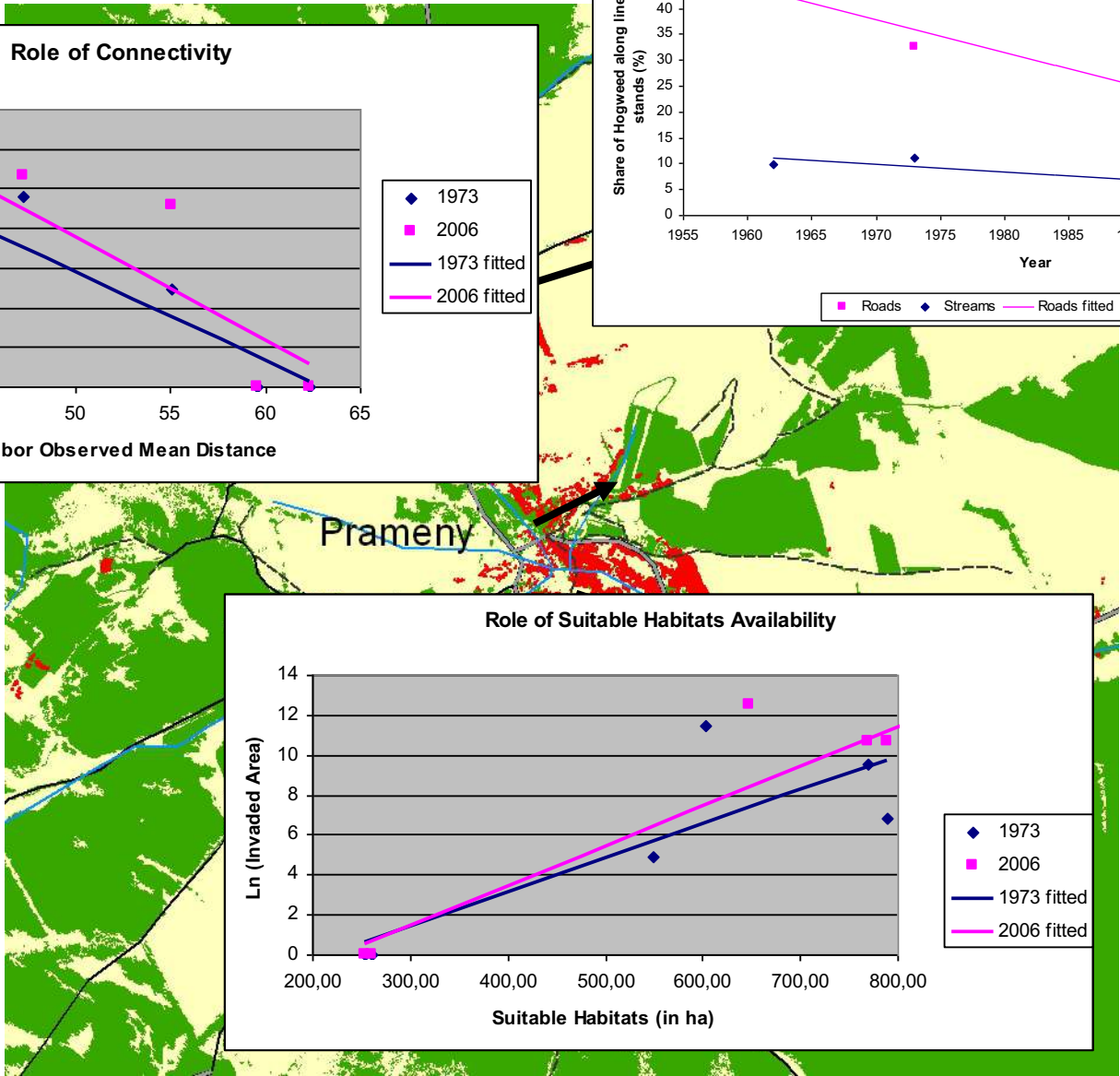


	1962	1973	1991	2006
Invaded area (ha)	73	131,2	269.5	606.7
Rate of areal spread (ha.year ⁻¹)	-	5,29	7,68	22,48
Rate of linear spread (m.year ⁻¹)	-	17,61	45,86	18,28

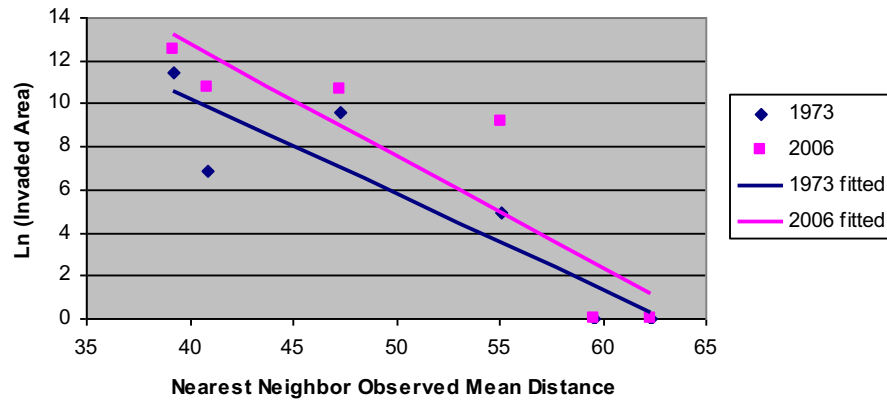


Process of invasion

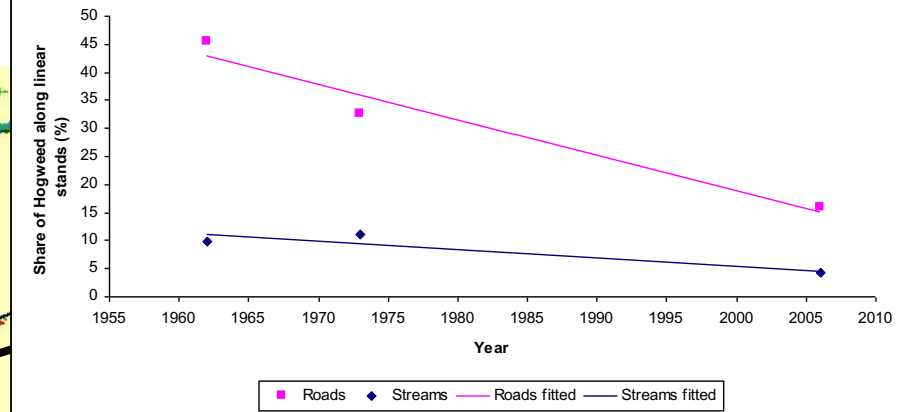




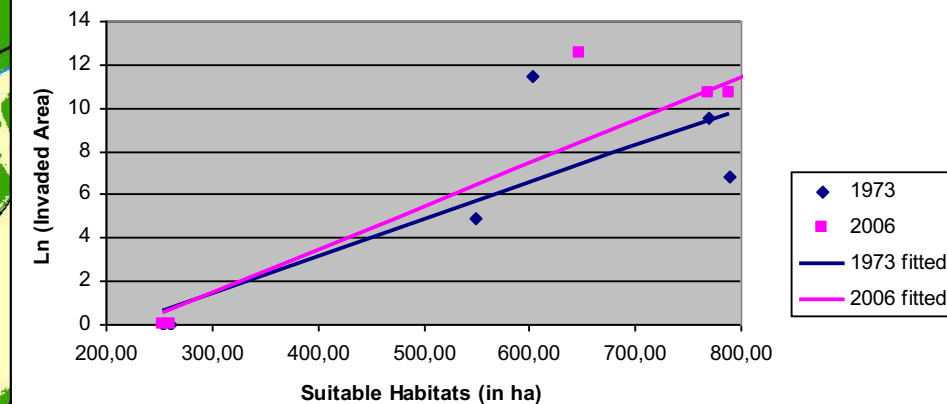
Role of Connectivity

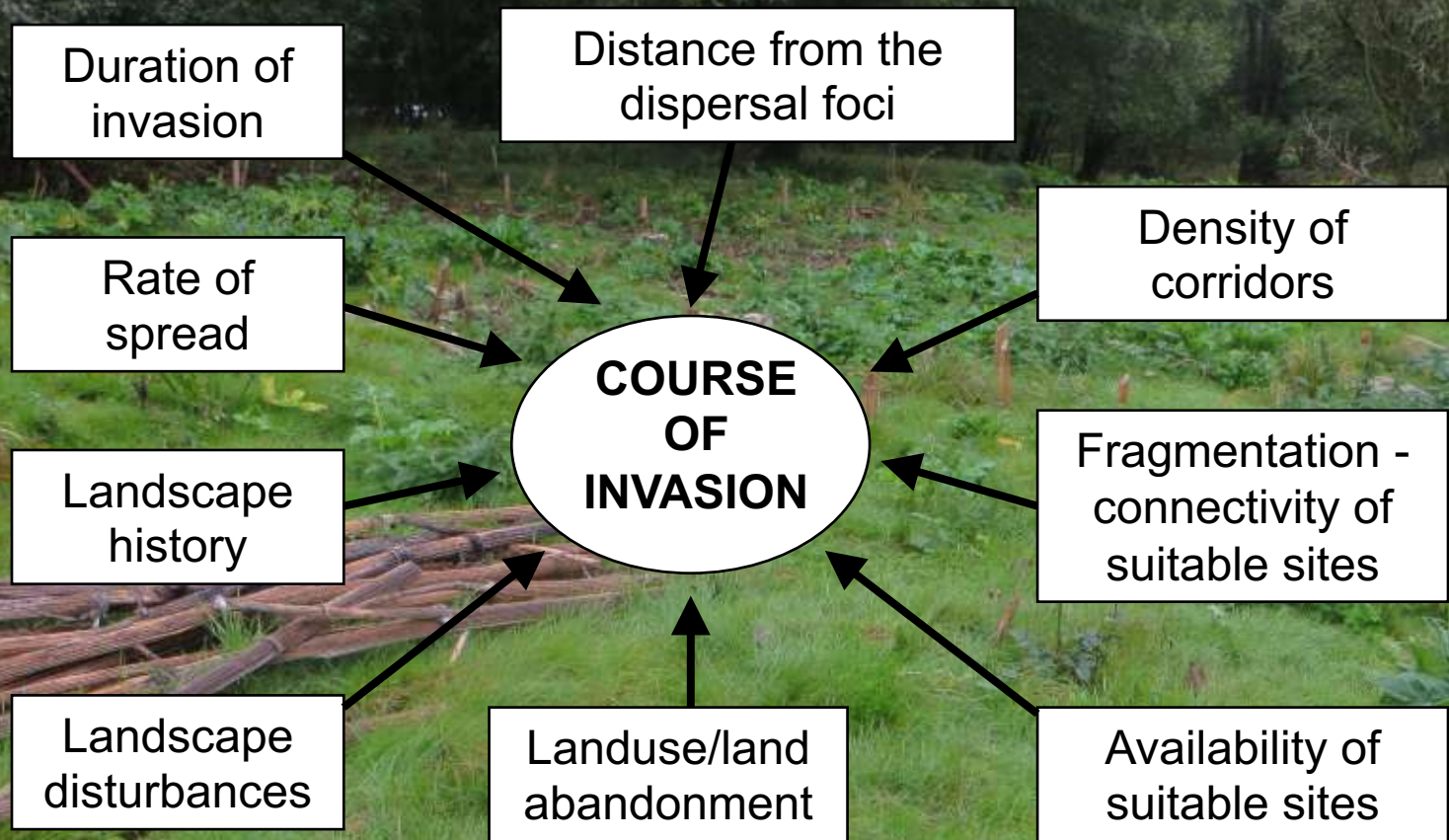


Role of Corridors



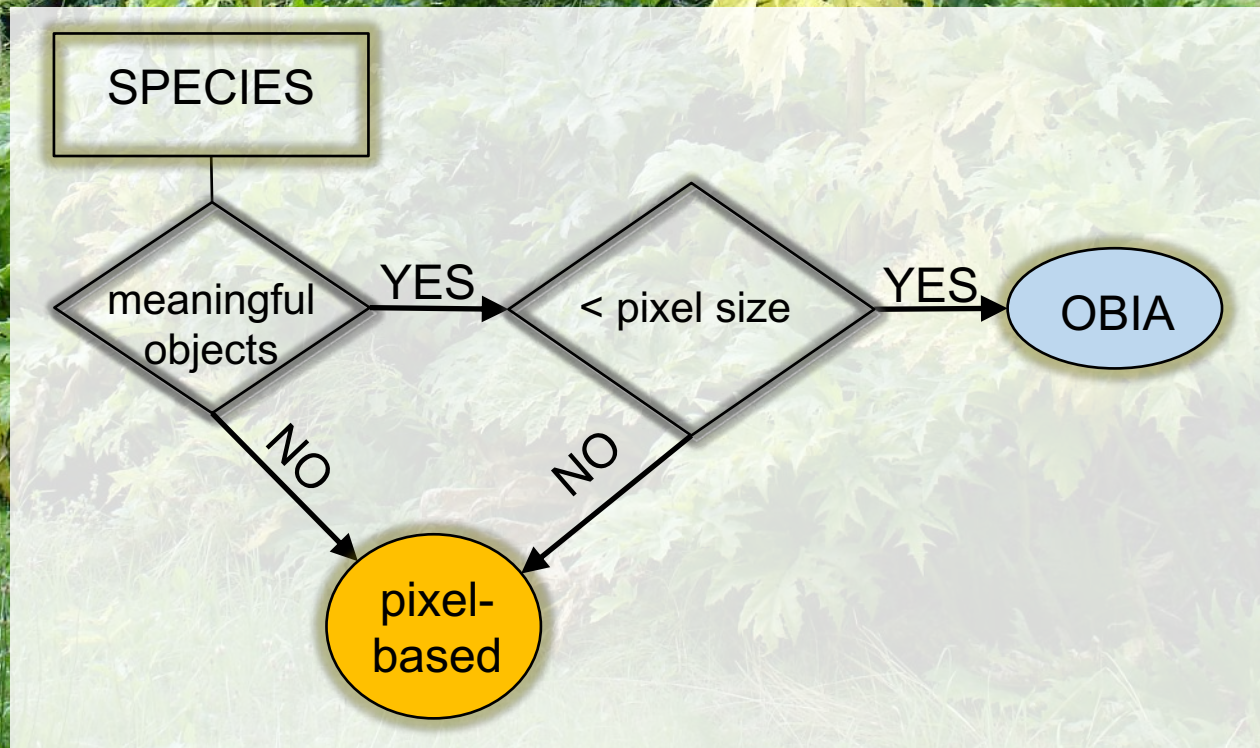
Role of Suitable Habitats Availability





Lessons learned, practical implications

1. RS advantages x limits
2. Methodology must reflect phenology, morphology and structure of the target plant



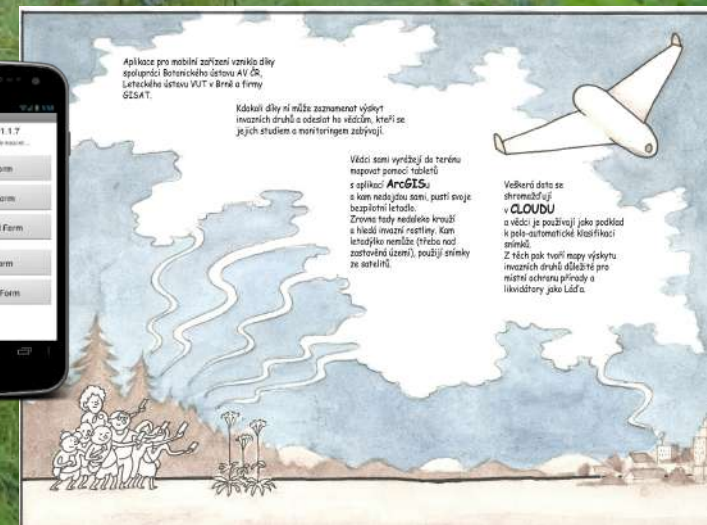
Lessons learned, practical implications

- 1. RS advantages x limits**
- 2. Methodology must reflect phenology, morphology and structure of the target plant**
- 3. Data choice - crucial, depends on the purpose**
- 4. Acceptable accuracy differs, depends on the purpose**
- 5. Trade-off between species and data**

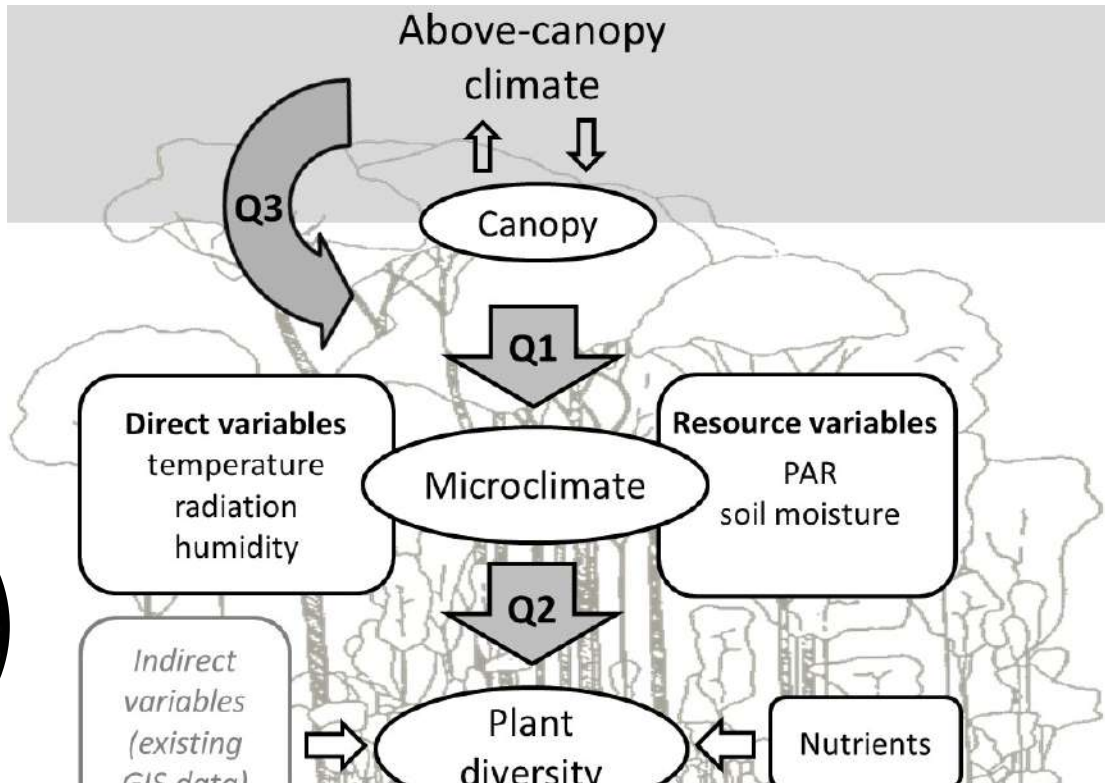


Current research

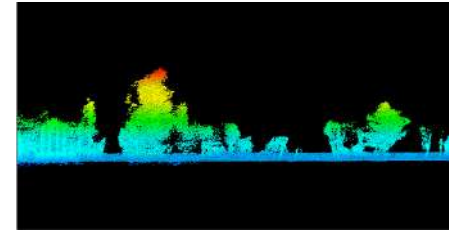
1. Assessing efficiency of eradication campaigns
2. Operational use of remote sensing in nature conservation
3. Role of the landscape history in shaping the invasion
4. Socio-economic impact of invasions
5. Engaging the public (citizen science, raising awareness)



Forest microclimate - neglected link between plant diversity and climate change



- 1) What is the range of microclimate variability at different spatial and temporal scales and how is it related to forest canopy cover?
- 2) How is plant diversity related to microclimate and canopy cover?
- 3) Is there a direct link between above and below-canopy climate?



Special Session

“RS of Vegetation for Biodiversity Research”



Thank you for your attention!

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